





RF-Sensing for ASL-Based Human Computer Interactions

Dr. Sevgi Zubeyde Gurbuz Lab for Computational Intelligence in Radar (CI4R) Dept. of Electrical and Computer Engineering The University of Alabama, Tuscaloosa, AL

szgurbuz@ua.edu
http://ci4r.ua.edu

August 19, 2022





Our Team



Sevgi Z. GurbuzElectrical Eng.
Univ. Alabama



Chris Crawford Computer Sci. Univ. Alabama



Evie MalaiaNeurolinguistics
Univ. Alabama



Darrin J. Griffin Communication Univ. Alabama



Ali C. Gurbuz Electrical Eng. Miss. State Univ.





Dr. Caroline Kobek-Pezzarossi

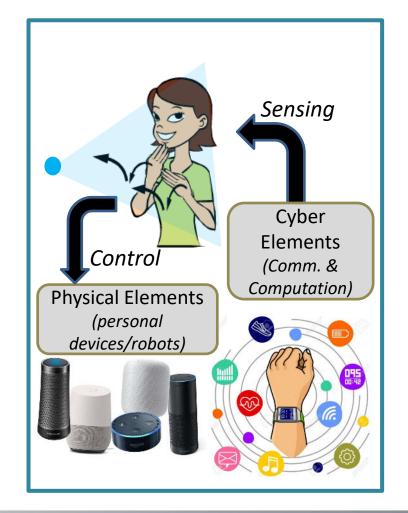


Dr. Kenneth De Haan



Objective

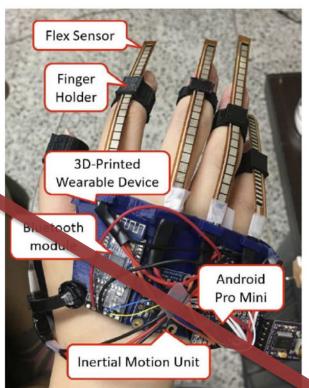
How can design technology to interact with humans via American Sign Language?





Wearables?





(c)Wearable system by (Lee18)



Video?







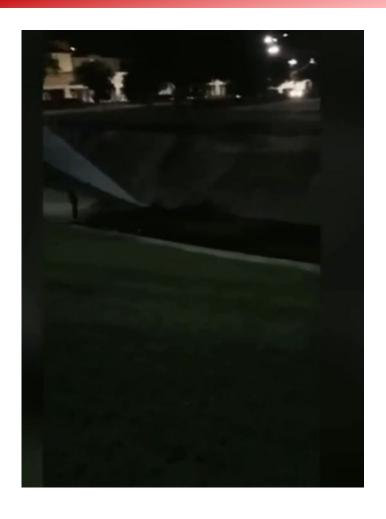








Limitations of Video





Not effective in the dark



Narrow field of view



Can be affected by skin tone or the color of the clothes you wear



Non-Contact Sensing

Radio Frequency (RF) Sensing

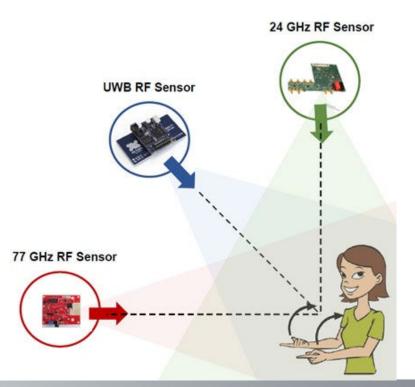
Non-Invasive, remote

Works day and night

Protects privacy

Wide field-of-view

Color-blind and not affected by clothes



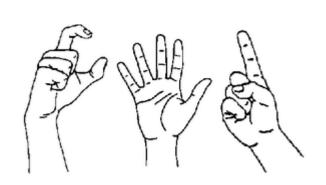


Limitations of RF Sensors





Cannot perceive facial expressions



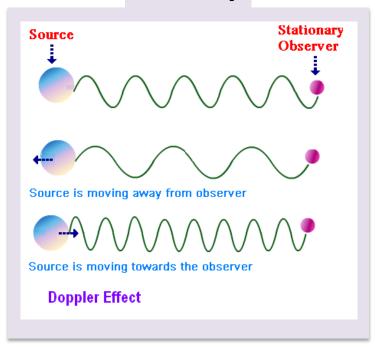


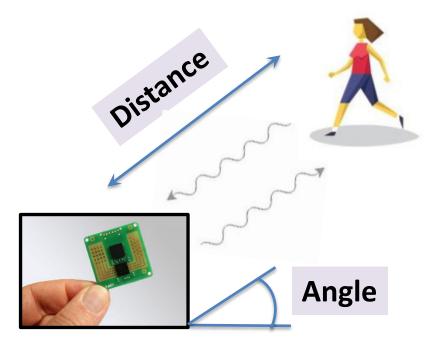
(Currently) cannot figure out hand shape



What do RF sensors measure?

Velocity



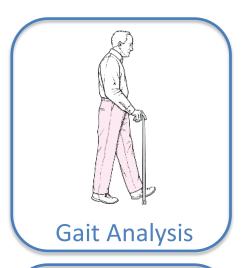






Example Applications of RF







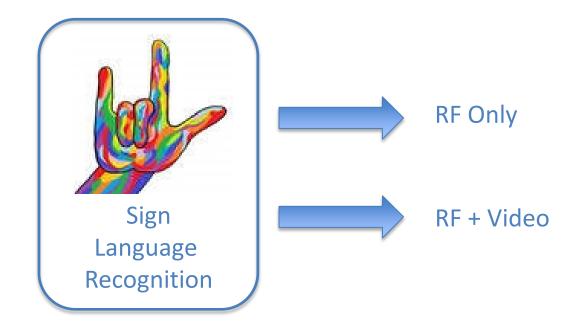






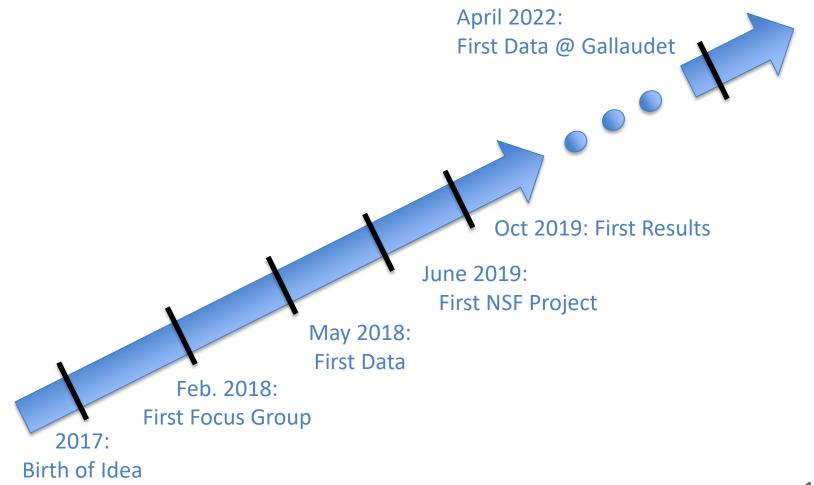


New RF Application





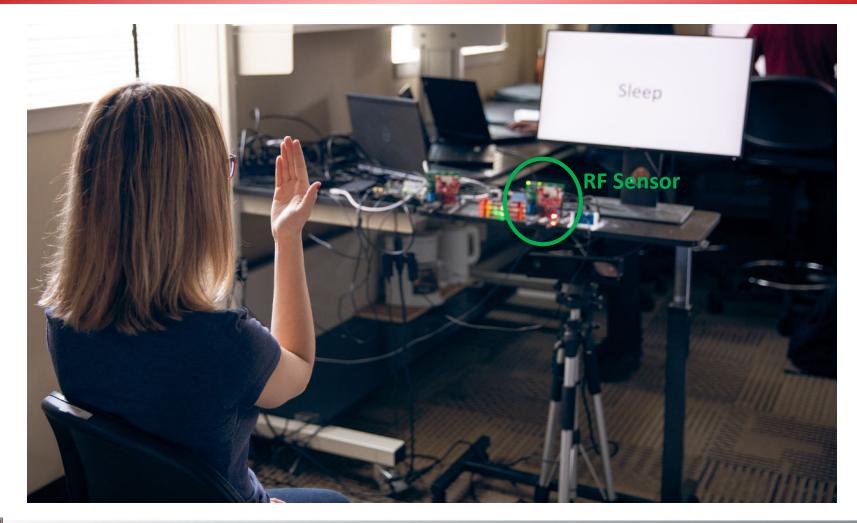
Evolution of Project







RF System

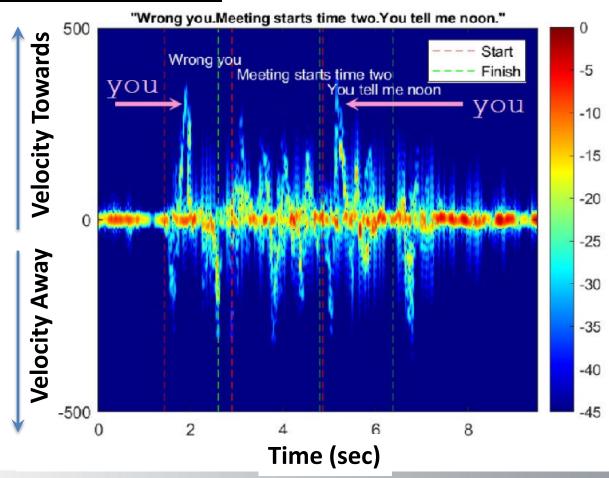






What Does RF Data Look Like?

Micro-Doppler Signature





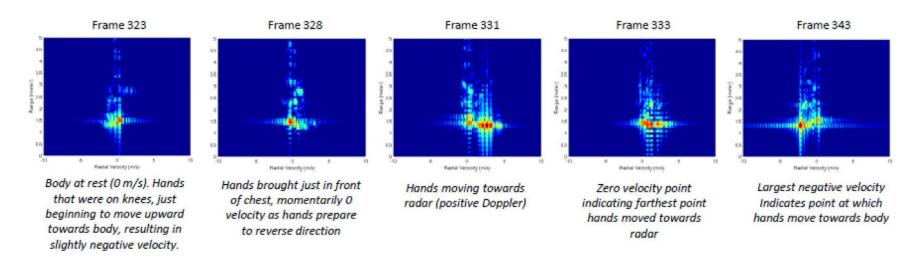
14



Another Way to Visualize RF Data

Distance-Velocity Maps

Snapshots of distance versus velocity at different times



Samples of sequential frames from Range-Doppler video for the breathe sign.



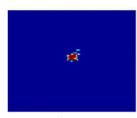
Other Ways to Visualize RF Data

Distance-Angle Maps

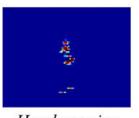
Snapshots of distance versus angle at different times



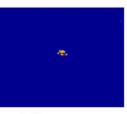
Subject is sitting stationary



Hands start to move



Hands moving towards the body



A short pause upon reaching the chest



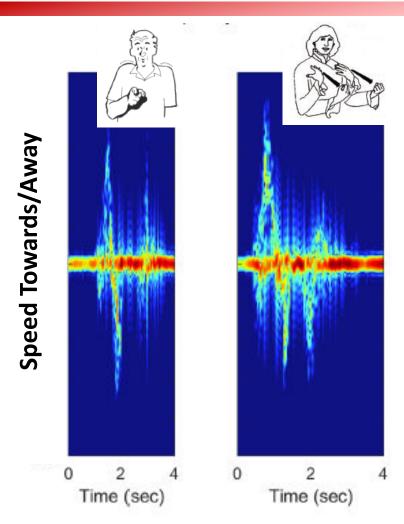
Retracting hands to original position



Sign completed



Sample ASL Signs in RF



Single or Two-Handed Signs

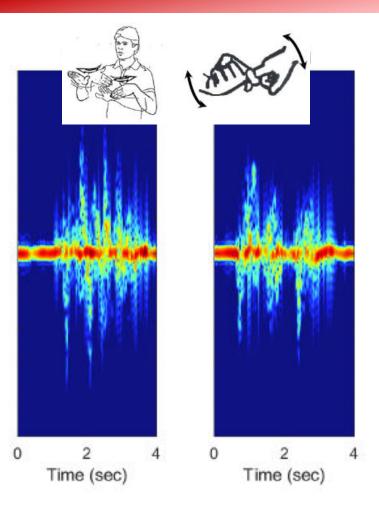
(where hands do similar things)

- Can tell if hands moved towards or away by whether data peaks upward or downward
- Dominant direction at any given time





Sample ASL Signs in RF (cont.)



Two Hands Moving Independently

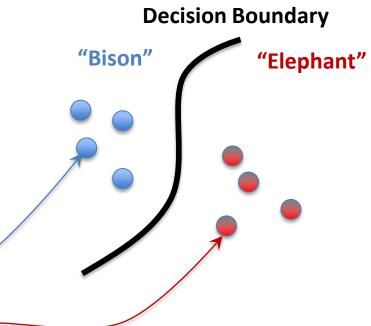
 Peaks in the data both upward and downward at the same time



How Do Computers Figure it Out?







Brown
Horns
Hoofs
White Shirt

Grey
Flappy Ears
Big Feet
Red Shirt

New Data: Which side is it on?





Approach: Deep Learning

Takes massive amounts of **DATA** for figuring out decision boundaries

- Roadmap for Rest of Talk:
 - Which data? The impact of fluency
 - Data Synthesis
 - Recognizing single words
 - Triggering and Controlling Devices
 - Future Directions





Interim Pause for Questions and Discussions

Let's Keep Going ☺



21



Imitation vs. Fluent

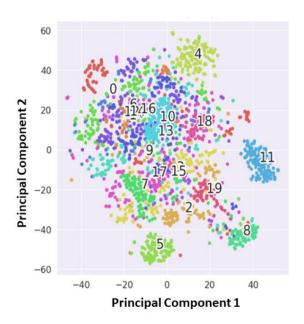
- Imitation Data:
 - Hearing person tries to sign after watching videos

- Fluent Signers:
 - Actually know ASL!





Imitation # Fluent



Imitation

Fluent

Computers

can differentiate

imitation signing

from

fluent ASL signing

with 76% accuracy





Can we effectively teach computers with imitation data?

NO

Case 1:

- Teach a computer with imitation data
- Test with imitation data

96%

20 ASL Signs

Case 2:

- Teach a computer with imitation data
- Test with fluent data

24%

Case 3:

- Teach a computer with fluent data
- Test with fluent data



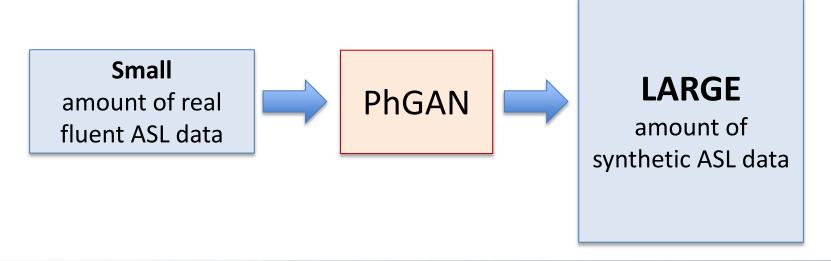
78%





Alternative Approach

- Teach computers using synthetic data
 - "Generative Adversarial Networks" (GANs)
 - We have developed new types of "Physics-Aware GANs" (PhGAN) specific to RF ASL data



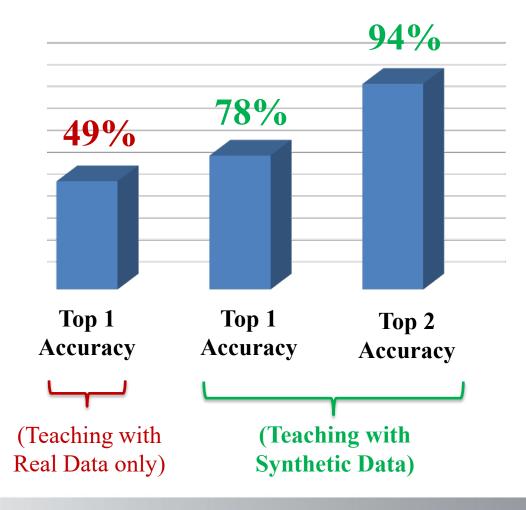


25



Single-Word ASL Results









How does this compare with video?

	Top-1	Top-5
RF (PhGAN)	78%	93%
Video (HRNet)	60%	90%





RF + Video

RF and Video provide different information

 RF: depth and azimuth distance + radial velocity (patterns of micro-Doppler)

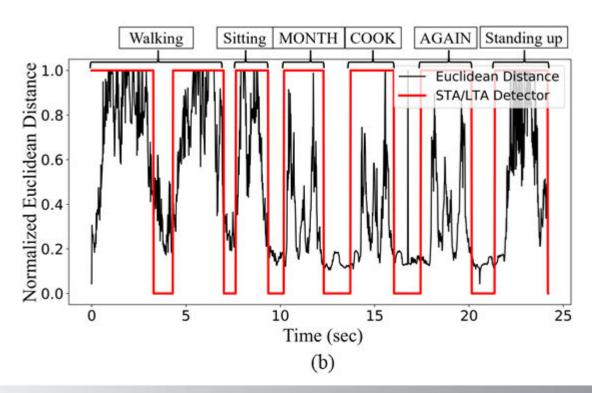
Video: spatial information, expressions
 (weak in depth and temporal resolution)





Triggering and Controlling Devices

- We can differentiate ASL from daily activity
 - Detect, segment, classify







What should trigger a device?

Initially explored signs more easily and consistently replicable

Words	Two- Handed	# of Strokes	Major Location	Movement
TIRED	√	3	Body	Curved
BOOK	✓	3	Neutral	Curved
SLEEP	✓	4	Head	Straight
EVENING	✓	5+	Hand	Straight
READY	✓	4	Neutral	Straight
НОТ	X	3	Head	Curved
MONTH	√	3	Hand	Straight
COOK	✓	5+	Hand	Other
AGAIN	✓	4	Hand	Curved
SUMMON	✓ .	3	Hand	Back-and-Forth
MAYBE	✓	5+	Neutral	Straight
NIGHT	V	3	Hand	Straight
SOMETHING	X	4	Neutral	Circular
TEACHER	✓	4	Head	Straight
TEACH	✓	3	Head	Straight



Trigger Sign Design

- Trigger sign design considerations
 - Cultural
 - Not easily confused with daily activity
 - Not easily confused with other conversation
 - For RF: more movement the better

NEED COMMUNITY INPUT / COLLABORATION





Work in Progress

- Interactive Gaming
- Continuous Discourse:
 - Properties
 - Semantic segmentation
- ASL-Triggered/Controlled Interface Prototype
- Sensor Fusion (RF+Video, RF+Lidar, RF+?)





Community Outreach

 STEM Education with the Alabama Institute of the Deaf and Blind and NTID Regional STEM Center







Thank you!

My research was supported in part by the National Science Foundation Cyber-Physical Systems Program Award #: 1932547 / 1931861



Sevgi Zubeyde Gurbuz

Assistant Professor
Computationally Intelligence for Radar (CI4R) Lab
Dept. of Electrical and Computer Engineering
University of Alabama – Tuscaloosa
szgurbuz@ua.edu

Visit us at: http://ci4r.ua.edu

